10 V/5.0 V Low Dropout Dual Regulator with ENABLE

The CS8147 is a 10 V/5.0 V dual output linear regulator. The 10V \pm 5.0% output sources 500 mA and the 5.0 V \pm 3% output sources 70 mA. The secondary output is inherently stable and does not require an external capacitor.

The on board $\overline{\text{ENABLE}}$ function controls the regulator's two outputs. When $\overline{\text{ENABLE}}$ is high, the regulator is placed in SLEEP mode. Both outputs are disabled and the regulator draws only 70 μ A of quiescent current.

The regulator is protected against overvoltage conditions. Both outputs are protected against short circuit and thermal runaway conditions.

The CS8147 is packaged in a 5 lead TO–220 with copper tab. The copper tab can be connected to a heat sink if necessary.

Features

- Two Regulated Outputs
 - 10 V ±5.0%; 500 mA
 - 5.0 V ±3.0%; 70 mA
- 70 µA SLEEP Mode Current
- Inherently Stable Secondary Output (No Output Capacitor Required)
- Fault Protection
 - Overvoltage Shutdown
 - Reverse Battery
 - 60 V Peak Transient
 - - 50 V Reverse Transient
 - Short Circuit
 - Thermal Shutdown
- CMOS Compatible ENABLE Input with Low (I_{OUT(max)}) Input Current



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TO-220 FIVE LEAD THA SUFFIX CASE 314A



ORDERING INFORMATION

Device	Package	Shipping
CS8147YT5	TO–220* STRAIGHT	50 Units/Rail
CS8147YTVA5	TO-220* VERTICAL	50 Units/Rail
CS8147YTHA5	TO–220* HORIZONTAL	50 Units/Rail
*Five lead	1	

*Five lead.



Figure 1. Block Diagram

ABSOLUTE MAXIMUM RATINGS*

Ratin	Value	Unit	
Input Voltage:	DC Positive Peak Transient Voltage (Note 1.) Negative Peak Transient Voltage	-18 to 26 60 -50	V V V
ESD (Human Body Model)		2.0	kV
ENABLE Input		-0.3 to 10	V
Internal Power Dissipation		Internally Limited	-
Junction Temperature Range		-40 to +150	°C
Storage Temperature Range		-65 to +150	°C
Lead Temperature Soldering:	Wave Solder (through hole styles only) (Note 2.)	260 peak	°C

1. 46 V Load Dump @ V_{IN} = 14 V

2. 10 second maximum.

*The maximum package power dissipation must be observed.

ELECTRICAL CHARACTERISTICS for VOUT:	$(V_{IN} = 14 \text{ V}, I_{OUT1} = I_{OUT2} = 5.0 \text{ mA}, -40^{\circ}\text{C} < T_{J} < 150^{\circ}\text{C},$
$-40^{\circ}C \le T_A \le 125^{\circ}C$, ENABLE = LOW; unless otherwis	

Characteristic	Test Conditions	Min	Тур	Max	Unit
Primary Output (V _{OUT1})					
Output Voltage	13 V \leq V $_{IN}$ \leq 26 V, I $_{OUT1}$ \leq 500 mA	9.50	10.00	10.5	V
Dropout Voltage	I _{OUT1} = 500 mA	-	0.5	0.7	V
Line Regulation	11 V \leq V _{IN} \leq 18 V, I _{OUT1} = 250 mA	-	45	90	mV
Load Regulation	$5.0 \text{ mA} \le I_{OUT1} \le 500 \text{ mA}$	_	15	75	mV
Quiescent Current	I_{OUT1} \leq 1.0 mA, No Load on $V_{OUT2},$ V_{IN} = 18 V I_{OUT1} = 500 mA, No Load on $V_{OUT2},$ V_{IN} = 11 V	_ _	3.0 60	7.0 120	mA mA
Quiescent Current	ENABLE = HIGH, V _{OUT1} , V _{OUT2} = OFF	_	70	200	μΑ
Current Limit	-	0.55	0.80	_	А
Long Term Stability	-	_	50	_	mV/kh
Overvoltage Shutdown	V _{OUT1} and V _{OUT2}	32	36	40	V
Secondary Output (V _{OUT2})					
Output Voltage	$6.0 \text{ V} \leq \text{V}_{\text{IN}} \leq 26 \text{ V}, 1.0 \text{ mA} \leq \text{I}_{\text{OUT2}} \leq 70 \text{ mA}$	4.85	5.00	5.15	V
Dropout Voltage	I _{OUT2} ≤ 70 mA	_	1.5	2.5	V
Line Regulation	$11 \le V_{IN} \le 18 \text{ V}, I_{OUT} = 70 \ \mu\text{A}$	_	4.0	50	mV
Load Regulation	$1.0 \text{ mA} \le I_{OUT2} \le 70 \text{ mA}, \text{ V}_{IN} = 14 \text{ V}$	_	10	50	mV
Current Limit	-	_	150	_	mA
ENABLE Function (ENABLE)					
Input ENABLE Threshold V _{OUT2(ON)} V _{OUT1(OFF)}		_ 0.8	1.40 1.40	2.50 -	V V
Input ENABLE Current	Input Voltage Range 0 to 5.0 V	-10	-	10	μA

PACKAGE LEAD #		
5 Lead TO-220	LEAD SYMBOL	FUNCTION
1	ENABLE	CMOS compatible input lead; switches V_{OUT1} and V_{OUT2} on and off. When $\overline{\text{ENABLE}}$ is low, V_{OUT1} and V_{OUT2} are active.
2	V _{IN}	Supply voltage, usually direct from battery.
3	GND	Ground connection.
4	V _{OUT1}	Regulated output 10 V, 500 mA (typ).
5	V _{OUT2}	Secondary output 5.0 V, 70 mA (typ).



TYPICAL PERFORMANCE CHARACTERISTICS



DEFINITION OF TERMS

Dropout Voltage – The input–output voltage differential at which the circuit ceases to regulate against further reduction in input voltage. Measured when the output voltage has dropped 100 mV from the nominal value obtained at 14 V input, dropout voltage is dependent upon load current and junction temperature.

Current Limit – Peak current that can be delivered to the output.

Input Voltage – The DC voltage applied to the input terminals with respect to ground.

Input Output Differential – The voltage difference between the unregulated input voltage and the regulated output voltage for which the regulator will operate.

Line Regulation – The change in output voltage for a change in the input voltage. The measurement is made under conditions of low dissipation or by using pulse techniques such that the average chip temperature is not significantly affected.

Load Regulation – The change in output voltage for a change in load current at constant chip temperature.

Long Term Stability – Output voltage stability under accelerated life–test conditions after 1000 hours with maximum rated voltage and junction temperature.

Output Noise Voltage – The rms AC voltage at the output, with constant load and no input ripple, measured over a specified frequency range.

Quiescent Current – The part of the positive input current that does not contribute to the positive load current. The regulator ground lead current.

Ripple Rejection – The ratio of the peak–to–peak input ripple voltage to the peak–to–peak output ripple voltage.

Temperature Stability of V_{OUT} – The percentage change in output voltage for a thermal variation from room temperature to either temperature extreme.



Figure 14. Typical Circuit Waveform



* C1 is required if the regulator is located away from the power source filter.

** C₂ is required for stability.

Figure 15. Test & Applications Circuit

APPLICATION NOTES

Since both outputs are controlled by the same $\overline{\text{ENABLE}}$, the CS8147 is ideal for applications where a sleep mode is required. Using the CS8147, a section of circuitry such as a display and nonessential 5.0 V circuits can be shut down under microprocessor control to conserve energy.

The test applications circuit diagram shows an automotive radio application where the display is powered by 10 V from V_{OUT1} and the Tuner IC is powered by 5.0 V from V_{OUT2} . Neither output is required unless both the ignition and the Radio On/OFF switch are on.

Stability Considerations

The secondary output V_{OUT2} is inherently stable and does not require a compensation capacitor. However a compensation capacitor connected between V_{OUT1} and ground is required for stability in most applications.

The output or compensation capacitor helps determine three main characteristics of a linear regulator: start–up delay, load transient response and loop stability.

The capacitor value and type should be based on cost, availability, size and temperature constraints. A tantalum or aluminum electrolytic capacitor is best, since a film or ceramic capacitor with almost zero ESR can cause instability. The aluminum electrolytic capacitor is the least expensive solution, but, if the circuit operates at low temperatures (-25° C to -40° C), both the value and ESR of the capacitor will vary considerably. The capacitor manufacturers data sheet usually provides this information.

The value for the output capacitor C2 shown in the test and applications circuit should work for most applications, however it is not necessarily the optimized solution.

To determine acceptable value for C2 for a particular application, start with a tantalum capacitor of the recommended value and work towards a less expensive alternative part.

Step 1: Place the completed circuit with a tantalum capacitor of the recommended value in an environmental chamber at the lowest specified operating temperature and monitor the outputs with an oscilloscope. A decade box connected in series with the capacitor will simulate the higher ESR of an aluminum capacitor. Leave the decade box outside the chamber, the small resistance added by the longer leads is negligible.

Step 2: With the input voltage at its maximum value, increase the load current slowly from zero to full load while observing the output for any oscillations. If no oscillations are observed, the capacitor is large enough to ensure a stable design under steady state conditions.

Step 3: Increase the ESR of the capacitor from zero using the decade box and vary the load current until oscillations appear. Record the values of load current and ESR that cause the greatest oscillation. This represents the worst case load conditions for the regulator at low temperature.

Step 4: Maintain the worst case load conditions set in step 3 and vary the input voltage until the oscillations increase.

This point represents the worst case input voltage conditions.

Step 5: If the capacitor is adequate, repeat steps 3 and 4 with the next smaller valued capacitor. A smaller capacitor will usually cost less and occupy less board space. If the output oscillates within the range of expected operating conditions, repeat steps 3 and 4 with the next larger standard capacitor value.

Step 6: Test the load transient response by switching in various loads at several frequencies to simulate its real working environment. Vary the ESR to reduce ringing.

Step 7: Raise the temperature to the highest specified operating temperature. Vary the load current as instructed in step 5 to test for any oscillations.

Once the minimum capacitor value with the maximum ESR is found for each output, a safety factor should be added to allow for the tolerance of the capacitor and any variations in regulator performance. Most good quality aluminum electrolytic capacitors have a tolerance of $\pm 20\%$ so the minimum value found should be increased by at least 50% to allow for this tolerance plus the variation which will occur at low temperatures. The ESR of the capacitors should be less than 50% of the maximum allowable ESR found in step 3 above.

Calculating Power Dissipation in a Dual Output Linear Regulator

The maximum power dissipation for a dual output regulator (Figure 16) is

$$\label{eq:PD(max)} \begin{array}{l} \mathsf{P}_{D(max)} = [\mathsf{VIN}(max) - \mathsf{VOUT1}(min)] \mathsf{IOUT1}(max) + \\ [\mathsf{VIN}(max) - \mathsf{VOUT2}(min)] \mathsf{IOUT2}(max) + \\ \mathsf{VIN}(max) \mathsf{IQ} \ \ (1) \end{array}$$

where:

V_{IN(max)} is the maximum input voltage,

 $V_{OUT1(min)}$ is the minimum output voltage from V_{OUT1} , $V_{OUT2(min)}$ is the minimum output voltage from V_{OUT2} ,

 $I_{OUT1(max)}$ is the maximum output current, for the application,

 $I_{OUT2(max)}$ is the maximum output current, for the application, and

 I_Q is the quiescent current the regulator consumes at $I_{OUT(max)}$.

Once the value of $P_{D(max)}$ is known, the maximum permissible value of $R_{\Theta JA}$ can be calculated:

$$R_{\Theta}JA = \frac{150^{\circ}C - T_{A}}{P_{D}}$$
⁽²⁾

The value of $R_{\Theta JA}$ can be compared with those in the package section of the data sheet. Those packages with $R_{\Theta JA}$'s less than the calculated value in equation 2 will keep the die temperature below 150°C.

In some cases, none of the packages will be sufficient to dissipate the heat generated by the IC, and an external heatsink will be required.



Figure 16. Dual Output Regulator With Key Performance Parameters Labeled.

Heat Sinks

A heat sink effectively increases the surface area of the package to improve the flow of heat away from the IC and into the surrounding air. Each material in the heat flow path between the IC and the outside environment will have a thermal resistance. Like series electrical resistances, these resistances are summed to determine the value of $R_{\Theta JA}$:

$$R_{\Theta JA} = R_{\Theta JC} + R_{\Theta CS} + R_{\Theta SA}$$
(3)

where:

 $R_{\Theta JC}$ = the junction–to–case thermal resistance,

 $R_{\Theta CS}$ = the case-to-heatsink thermal resistance, and

 $R_{\Theta SA}$ = the heatsink-to-ambient thermal resistance.

 $R_{\Theta JC}$ appears in the package section of the data sheet. Like $R_{\Theta JA}$, it too is a function of package type. $R_{\Theta CS}$ and $R_{\Theta SA}$ are functions of the package type, heatsink and the interface between them. These values appear in heat sink data sheets of heat sink manufacturers.

PACKAGE DIMENSIONS

TO-220 **FIVE LEAD T SUFFIX** CASE 314D-04 ISSUE E



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	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.572	0.613	14.529	15.570
В	0.390	0.415	9.906	10.541
С	0.170	0.180	4.318	4.572
D	0.025	0.038	0.635	0.965
Е	0.048	0.055	1.219	1.397
G	0.067 BSC		1.702 BSC	
Н	0.087	0.112	2.210	2.845
J	0.015	0.025	0.381	0.635
K	0.990	1.045	25.146	26.543
L	0.320	0.365	8.128	9.271
Q	0.140	0.153	3.556	3.886
U	0.105	0.117	2.667	2.972

TO-220 **FIVE LEAD TVA SUFFIX** CASE 314K-01 ISSUE O







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	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.560	0.590	14.22	14.99
В	0.385	0.415	9.78	10.54
С	0.160	0.190	4.06	4.83
D	0.027	0.037	0.69	0.94
Е	0.045	0.055	1.14	1.40
F	0.530	0.545	13.46	13.84
G	0.067	BSC	1.70 BSC	
J	0.014	0.022	0.36	0.56
Κ	0.785	0.800	19.94	20.32
L	0.321	0.337	8.15	8.56
М	0.063	0.078	1.60	1.98
Q	0.146	0.156	3.71	3.96
R	0.271	0.321	6.88	8.15
S	0.146	0.196	3.71	4.98
U	0.460	0.475	11.68	12.07
W	5	0	5	; °

TO-220 **FIVE LEAD** THA SUFFIX CASE 314A-03 ISSUE E



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	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.572	0.613	14.529	15.570
В	0.390	0.415	9.906	10.541
С	0.170	0.180	4.318	4.572
D	0.025	0.038	0.635	0.965
Е	0.048	0.055	1.219	1.397
F	0.570	0.585	14.478	14.859
G	0.067 BSC		1.702 BSC	
J	0.015	0.025	0.381	0.635
Κ	0.730	0.745	18.542	18.923
L	0.320	0.365	8.128	9.271
Q	0.140	0.153	3.556	3.886
S	0.210	0.260	5.334	6.604
U	0.468	0.505	11.888	12.827

PACKAGE THERMAL DATA

Parameter		TO-220	Unit
R _{OJC}	Typical	2.4	°C/W
R _{OJA}	Typical	50	°C/W

<u>Notes</u>

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